

Recall from last time that we had a multisymplectic manifold  $(X, \omega)$ ;  $\omega$  is a multisymplectic 3-form.

Also, we had a set of 1-forms  $\text{Ham}(X, \omega)$ :

$$\alpha \in \text{Ham}(X, \omega) \implies \exists v_\alpha \in \text{Vect}(X) \text{ s.t.}$$

$$d\alpha = -\omega(v_\alpha, -, -). \quad \text{Lastly, we had two}$$

bracket operations

$$\{\alpha, \beta\} := \text{Lie}_{v_\alpha} \beta$$

⋮

$$\{\alpha, \beta\}' := \omega(v_\alpha, v_\beta, -).$$

We showed how  $(\text{Ham}(X), \{\cdot, \cdot\})$  &  $(\text{Ham}(X), \{\cdot, \cdot\}')$

are weak Lie 2-algebras, i.e. a category with

- objects as elements of  $\text{Ham}(X)$
- morphisms in  $\text{Ham}(X) \oplus C^\infty(X)$

$$\alpha \xrightarrow{(\alpha, f)} \alpha + df$$

- $\{\cdot, \cdot\}$  (resp.  $\{\cdot, \cdot\}'$ ) is a bilinear functor

- a natural transformation

$$S : \{ \cdot, \cdot \} \implies - \{ \cdot, \cdot \} * \sigma \quad (\text{alternator})$$

(resp. for  $\{ \cdot, \cdot \}'$ )

- a natural transformation

$$J : \{ \cdot, \{ \cdot, \cdot \} \} \implies \{ \{ \cdot, \cdot \}, \cdot \} + \{ \cdot, \{ \cdot, \cdot \} \} * \sigma_{12} \quad (\text{Jacobiator})$$

For  $(\text{Ham}(X), \{ \cdot, \cdot \})$ , we have nontrivial  $S$  but  $J = 1$ .

For  $(\text{Ham}(X), \{ \cdot, \cdot \}')$ , we have trivial  $S$ , but non-trivial  $J$ .

Theorem: (Baez, Hoffnung, Rogers)

$(\text{Ham}(X), \{ \cdot, \cdot \}) \cong (\text{Ham}(X), \{ \cdot, \cdot \}')$  are isomorphic as weak Lie 2-algebras.

One of our motivations is to develop a geometric picture of classical string dynamics in analogy with classical particles & symplectic geometry.

Example: A non-relativistic (classical) string with 1 transverse degree of freedom (i.e. wiggles in only 1 direction.)



time

$t = 0$

$t = 1$

$t = 2$

To describe the configurations of the string, we define a function

$$\phi : \mathbb{R} \times [a, b] \longrightarrow \mathbb{R}$$

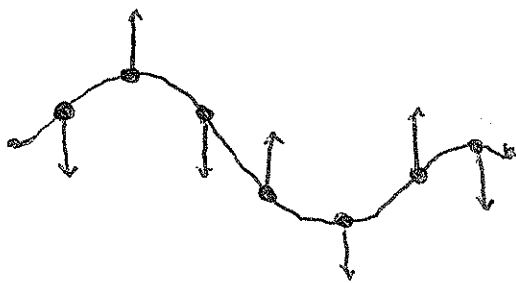
$\phi(t, \sigma)$  is the amplitude of the string at time  $t$  & position  $\sigma$ .

(4)

At each time  $\tau$ , we can make measurements of things like energy, "wave momentum", etc.

To figure out the formula for the energy:  
pretend the string is composed of "beads":

figure out the kinetic energy:



Each bead is a classical particle:

each bead will have kinetic energy  $\frac{1}{2} m v_i^2$

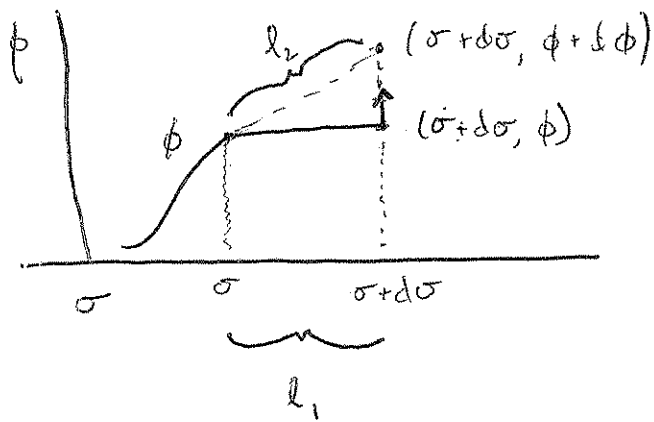
with  $v_i = \frac{\partial \phi(\tau, \sigma_i)}{\partial \tau}$

So we have total kinetic energy

$$T = \sum_{i=1}^N \frac{1}{2} m \left( \frac{\partial \phi}{\partial \tau} \right)^2 = \frac{1}{2} \int_a^b \left( \frac{\partial \phi}{\partial \tau} \right)^2 d\sigma$$

(take  $m=1$ )

For potential energy:



$$l_1 = d\sigma$$

$$l_2 = \left( (d\sigma)^2 + (d\phi)^2 \right)^{1/2}$$

$$\Delta l = l_2 - l_1$$

$$= d\sigma \left[ \left( 1 + \left( \frac{d\phi}{d\sigma} \right)^2 \right)^{1/2} - 1 \right]$$

Now we Taylor expand  $x^{1/2}$ :

$$\Delta l \approx d\sigma \left[ 1 + \frac{1}{2} \left( \frac{d\phi}{d\sigma} \right)^2 - 1 + \dots \right]$$

$$\approx d\sigma \frac{1}{2} \left( \frac{d\phi}{d\sigma} \right)^2$$

So

$$V = \int_a^b \frac{1}{2} \left( \frac{d\phi}{d\sigma} \right)^2 d\sigma$$

Therefore the energy of the string at time  $\bar{t}$  is

$$\mathcal{H} = \frac{1}{2} \int_a^b \left[ \left( \frac{\partial \phi}{\partial \tau} \right)^2 + \left( \frac{\partial \phi}{\partial \sigma} \right)^2 \right] d\sigma$$

Allowed configurations are given by the wave equation ⑥

$$\frac{\partial^2 \phi}{\partial \tau^2} - \frac{\partial^2 \phi}{\partial \sigma^2} = 0$$

(plus boundary data.)

Possible geometric pictures to describe string dynamics.

(1) Let  $M$  be the space of all possible string configurations.

(i.e. maps from  $[a, b]$  to  $\mathbb{R}$ )

We could then describe dynamics as a path

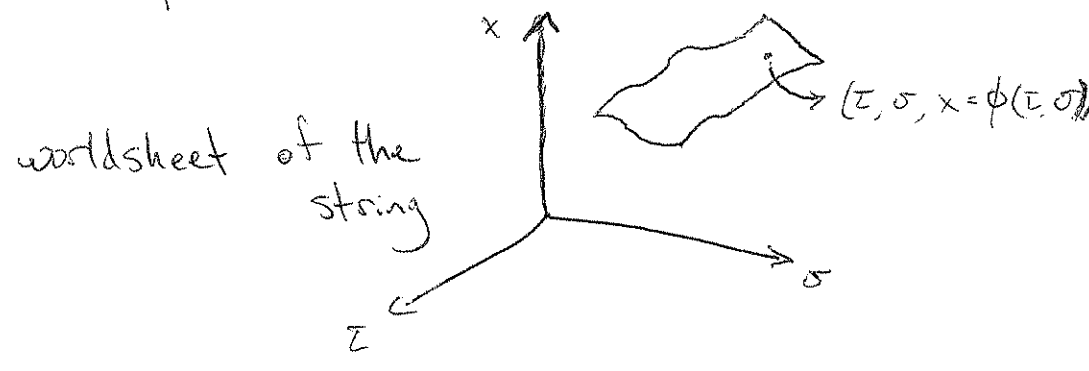
$$\chi: \mathbb{R} \rightarrow M$$

where  $\chi(t)$  is the configuration space of the string at time  $t$ .

Problem:  $\dim(M) = \infty$

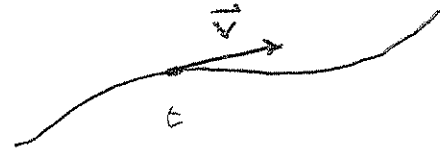
If you want to quantize the string,  $M$  is a bad place to do it.

(2) "A space-time picture"



So solutions to the wave equation are submanifolds.

- This is called the extended configuration space.
- Every particle has a velocity at a point on its worldline:



- Every point on the string worldsheet has a "velocity" bivector.

The phase space for the string:

at every point we get momentum data attached

$P_z, P_\sigma$

So our phase space is:

$$\begin{array}{ccccc}
 X & = & \mathbb{R}^2 & \times & \mathbb{R} & \times & \mathbb{R}^2 \\
 & & \downarrow & & \downarrow & & \downarrow \\
 & & (\tau, \sigma) & & (x) & & (p_\tau, p_\sigma)
 \end{array}$$

In  $X$ , there is a submanifold  $\Sigma$  with coordinates

$$(\tau, \sigma, x = \phi(\tau, \sigma), p_\tau = \pi_\tau, p_\sigma = \pi_\sigma)$$

with

$$\pi_\tau = \frac{\partial \phi}{\partial \tau}, \quad \pi_\sigma = -\frac{\partial \phi}{\partial \sigma}$$

• Define a 2-form on  $X$ :

$$\begin{aligned}
 \Theta &= \frac{1}{2} (p_\tau^2 - p_\sigma^2) d\tau \wedge d\sigma \\
 &\quad - p_\tau dx \wedge d\sigma + p_\sigma dx \wedge d\tau
 \end{aligned}$$

Let  $\omega = d\Theta$ :

$$\begin{aligned}
 \omega &= (p_\tau dp_\tau - p_\sigma dp_\sigma) \wedge d\tau \wedge d\sigma \\
 &\quad - dp_\tau \wedge dx \wedge d\sigma + dp_\sigma \wedge dx \wedge d\tau
 \end{aligned}$$

$\omega$  is clearly closed

$\omega$  is non degenerate:

$$\text{Let } v = v_t \frac{d}{dt} + v_\sigma \frac{d}{d\sigma} + v_x \frac{d}{dx} \\ + v_{p_t} \frac{d}{dp_t} + v_{p_\sigma} \frac{d}{dp_\sigma}$$

Assume  $\omega(v, -, -) = 0$  ; check that  $v = 0$ .

So  $\omega$  is a symplectic 3-form.

Given a function we can find a bivector field from  $\omega$  s.t. the bivector field corresponds to solutions of the wave equation.

We want to show that  $\text{Ham}(X)$  contains observables:

$$\text{Let } v_t = \frac{d}{dt} \text{ (coordinate vector in the time direction)}$$

Define a 1-form  $\mathcal{H} := \Theta(v_t, -)$

$$\mathcal{H} = \frac{1}{2} (p_t^2 - p_\sigma^2) d\sigma - p_\sigma dx$$

What is  $\text{Lie}_{v_t} \Theta$  ?

$$\text{Lie}_{v_t} \Theta = 0$$

Using the Weil identity:

$$\text{Lie}_{v_\tau} \theta = d i_{v_\tau} \theta + i_{v_\tau} d\theta = 0$$

but  $i_{v_\tau} \theta = \theta(v_\tau, -) =: \mathcal{H}$  ;  $d\theta = \omega$

which implies

$$d\mathcal{H} + i_{v_\tau} \omega = 0$$

$$\implies d\mathcal{H} = -i_{v_\tau} \omega$$

So  $\mathcal{H} \in \text{Ham}(X)$

We want to show this is in the set of observables:

- Pick a "slice" of  $\Sigma$  that is at constant time  $\tau_0$ ; called  $\Sigma_{\tau_0}$

A point on  $\Sigma_{\tau_0}$  is  $(\tau_0, \sigma, \phi(\tau_0, \sigma), \pi_\tau(\tau_0, \sigma), \pi_\sigma(\tau_0, \sigma))$

;

$$\mathcal{H} = \frac{1}{2} (\pi_\tau^2 - \pi_\sigma^2) - \pi_\sigma d\phi$$

;

$$d\phi = \frac{\partial \phi}{\partial \sigma} d\sigma + \frac{\partial \phi}{\partial \tau} d\tau$$

but  $d\tau = 0$

So  $d\phi = -\pi_\sigma d\sigma$ .

